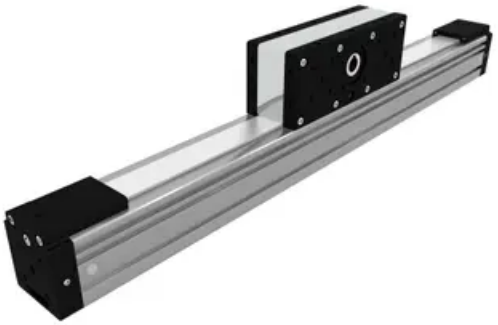
Linear Unit MTJZ 80

The MTJZ series contains Z-axis linear units with toothed belt drive, integrated ball rail system and compact dimensions. This linear units provide high performance features such as, high speed, good accuracy and repeatability by vertical applications.



In the linear units MTJZ is used a pre-tensioned steel reinforced AT polyurethane timing toothed belt. In conjunction with a zero-backlash drive pulley high moments with alternating loads with good positioning accuracy, low wear and low noise can be realized.

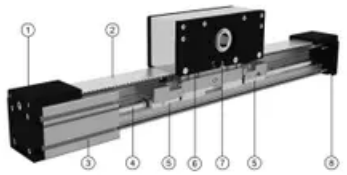
The in the profile slot driving timing belt protects all the parts in the profile from dust and other contaminations. The drive block provides the possibility to attach a motor or gearbox housing and additional accessories on it.

For CAD-files please contact Rollco.

Dimensions in mm.

Modulus of Elasticity: E = 70000 N / mm2
Operating Temperature (°C): 0 ~ +60 For operating temperature out of the presented range, please contact Rollco.
Duty Cycle: 100%
Max. Acceleration (m/s²): 70
Max. Travel Speed (m/s): 5

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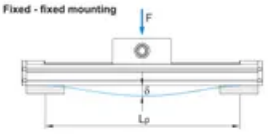


1. Tension End with integrated belt tensionin system
2. AT polyurethane toothed belt with steel tension cords
3. Aluminium profile - hard anodized
4. Linear ball guideway
5. Clamping and braking element for linear guideway
6. Drive block with pulley. Motor flange with built in magnets
7. Central lubrication port, both sides
8. Tension end with integrated belt tensioning system

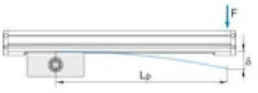
Deflection of the linear unit

MTJZ

Fixed - fixed mounting



Fixed - free mounting

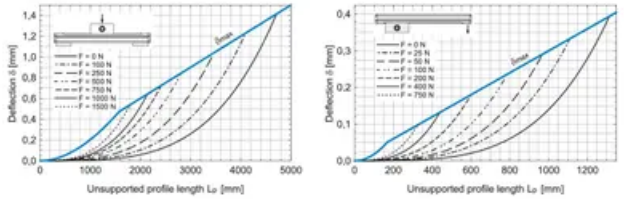


δ Maximum deflection of the linear unit [mm]
δmax Maximum permissible deflection of the linear unit [mm]
F Applied force [N]
Lp Unsupported profile length [mm]

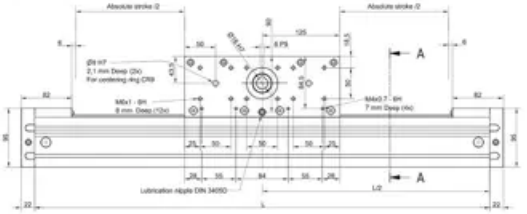
The maximum permissible deflection δmax must not be exceeded. In the case that maximum deflection δ exceeds the maximum permissible deflection δmax additional profile supports are needed.

Deflection of the linear unit

MTJZ 80

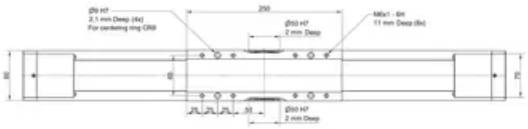


① *The linear units do not include any safetey stroke.*
Absolut stroke = Effective stroke + 2 x safety stroke.



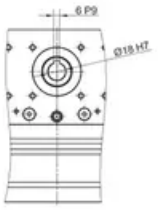
① *All dimensions in mm. Drawings scales are not equal.*

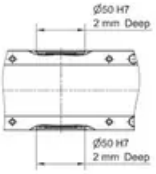
① *The linear units do not include any safetey stroke.*
Absolut stroke = Effective stroke + 2 x safety stroke.



① *All dimensions in mm. Drawings scales are not equal.*

TYPE 0

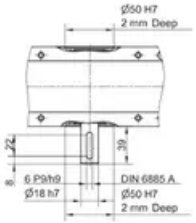




TYPE 1



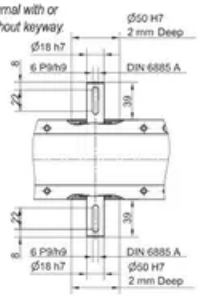
① *Journal with or without keyway.*



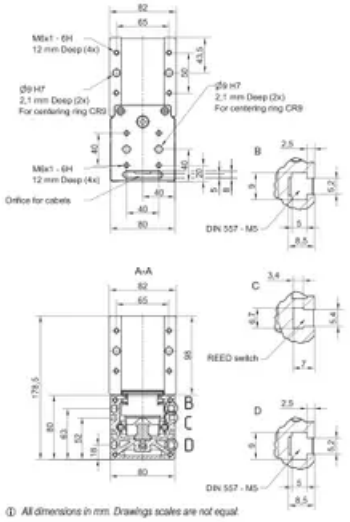
TYPE 2

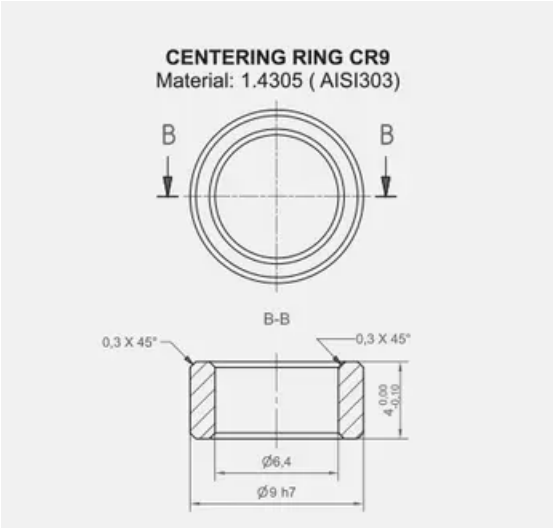


① *Journal with or without keyway.*



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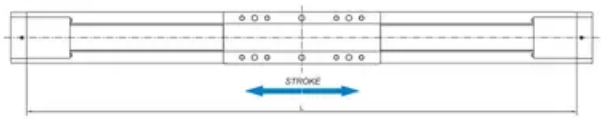




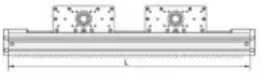
Defining of the linear unit length

L = Effective stroke + 2 × Safety stroke + 382 mm

Ltotal = L + 44 mm



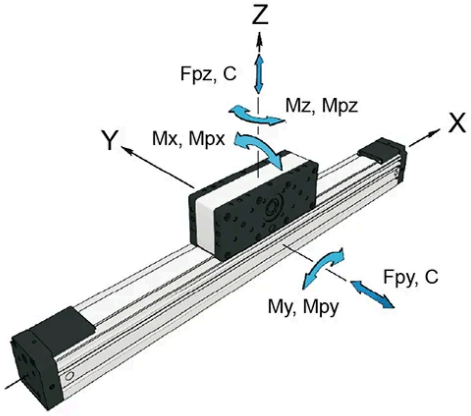
Multi drive block



L = Effective stroke + 2 × Safety stroke + 250 × n_b + 132 mm — n_b - number of drive blocks

Ltotal = L + 44 mm

General Data



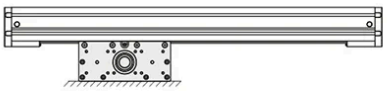
For minimum stroke below the stated value, please contact Rollco.

For length/stroke over the stated value, please contact Rollco. Values for max. stroke are not valid for multi drive box (equation of defining the linear unit length for particular size of the linear unit needs to be used).

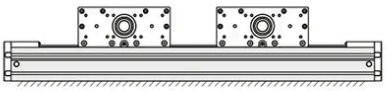
Recommended values of loads

All the data of static and dynamic moments and load capacities stated are theoretical without considering any safety factor. The safety factor depends on the application and its requested safety. We recommend a minimum safety factor (fs =5.0).

Version 1: *Mounting by the drive block, profile travels*



Version 2: *Mounting by the profile, drive block travels*



0n request, multi drive blocks, which travel independently of each other, can be applied.

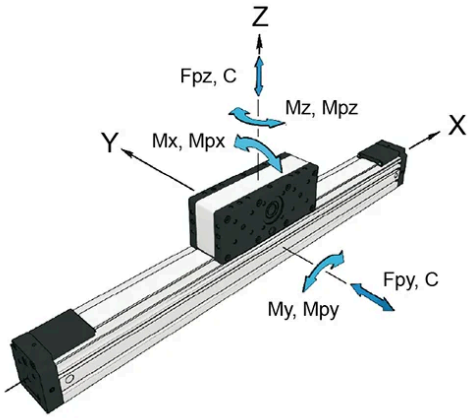
Designation	Dynamic Load Capacity C (N)	Static Load Capacity C0 (N)	Dynamic Moment Mx (Nm)	Dynamic Moment My (Nm)	Dynamic Moment Mz (Nm)
MTJZ 80	34200	60000	370	2565	2565

Designation	Mass of Drive Block (kg)	Max. Permissible Loads Forces Fpy (N)	Max. Permissible Loads Forces Fpz (N)	Max. Permissible Loads Moments Mpx (Nm)	Max. Permissible Loads Moments Mpy (Nm)	Max. Permissible Loads Moments Mpz (Nm)
MTJZ 80	4.9	8930	7130	150	535	670

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Designation	Max. Repeatability (mm)	Max. Length Version 1 Lmax (mm)	Max. Length Version 2 Lmax (mm)	Max. Stroke Version 1 (mm)	Max. Stroke Version 2 (mm)	Min. Stroke (mm)
MTJZ 80	± 0.08	1500	6000	1118	5618	55

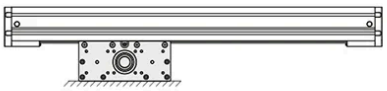
Drive Data



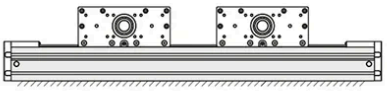
Max. acceleration (m/s2): 70*

For acceleration over the stated value, please contact Rollco.

Version 1: *Mounting by the drive block, profile travels*



Version 2: *Mounting by the profile, drive block travels*

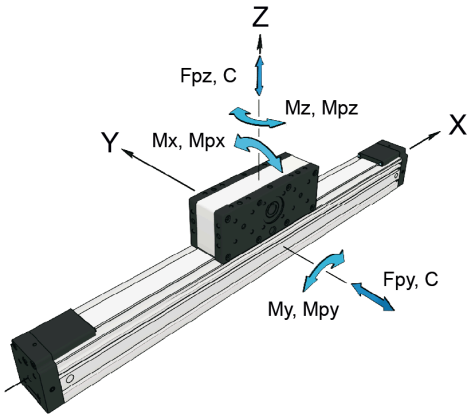


0n request, multi drive blocks, which travel independently of each other, can be applied.

Designation	Max. Drive Torque (Nm)	Pulley Drive Ratio (mm/rev)	Pulley Diameter	Planar Moment of Inertia ly (cm^4)	Planar Moment of Inertia lz (cm^4)
MTJZ 80	29.4	210	66.84	129.1	173.4

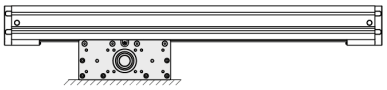
Designation	Belt Type	Belt Width	Max. Force Transmitted by Belt (N)	Specific Spring Constant Cspec (N)
MTJZ 80	AT5	50	880	960000

Mass and Mass Moment

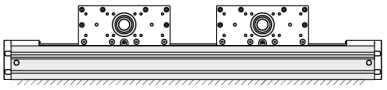


Mass calculation does not include mass of motor, reduction gear, switches and clamps.

Version 1: *Mounting by the drive block, profile travels*



Version 2: *Mounting by the profile, drive block travels*



0n request, multi drive blocks, which travel independently of each other, can be applied.

Abs. stroke	Absolute stroke [mm]
A	Distance between two drive blocks [mm]
nb	Number of drive blocks

Designation	Mass of Linear Unit (kg)	Mass Moment of Inertia Version 1 (10^{-4} kg m^2)	Mass Moment of Inertia of Drive Block Version 2 (10^{-4} kg m^2)	Planar Moment of Inertia ly (cm^4)	Planar Moment of Inertia lz (cm^4)
MTJZ 80	9.7 + 0.0083 × (Abs. Stroke + (nb - 1) × A) + 4.9 × (nb - 1)	60.0 + 0.0922 × (Abs. Stroke + (nb - 1) × A) + 6.4 × (nb - 1)	61.1	129.1	173.4

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